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In mathematics – specifically, in
differential equations – the
Picard–Lindelöf theorem, Picard's
existence theorem, Cauchy–Lipschitz
theorem, or existence and uniqueness
theorem gives a set of conditions

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under which an initial value problem has a unique solution. The theorem is named after Émile Picard, Ernst Lindelöf, Rudolf Lipschitz and Augustin-Louis Cauchy.

Picard–Lindelöf theorem - Wikipedia

Theorem 1 may be carried through with the new g , 2 functions essentially unchanged. THEOREM 2. Suppose $A(t, y)$ is continuous in t and Lipschitz in y and the functional $g(t, y)$ is Lipschitz continuous in t and y . Then, t_f, j are Lipschitz continuous on $[a, b]$ and satisfy $y_6g(t_5, L_y, Y) + uq(t_5, 5; yLF) + \sim \sim Y \sim$

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Synopsis. Theorems stating the existence of an object—such as the solution to a problem or equation—are known as existence theorems. This text examines fundamental and general existence theorems, along with the Picard iterants, and applies them to properties of solutions and linear differential equations. The authors assume a basic knowledge of real function theory, and for certain

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Subsection 1.6.1 The Existence and Uniqueness Theorem. The following theorem tells us that solutions to first-order differential equations exist and are unique under certain reasonable conditions. Theorem 1.6.1. Existence and Uniqueness Theorem. Let $(x' = f(t, x))$ have the initial condition $(x(t_0) = x_0 \text{ text{.}})$

Existence and Uniqueness of Solutions

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